

# Offline Verification of Hand Written Signature using Adaptive Resonance Theory Net (Type-1)

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**Abstract**— Recognizing hand-written signature is important due to several legal issues. Manual verification is often difficult when very much ‘similar-looking’ but forged signature is produced. In this work an effort has been made to automate such kind of signature verification process offline, using Adaptive Resonance Theory type-1 (ART-1). It is implemented using both serial and parallel processing, the performance of which are then compared. The said network has been trained with the original signature and tested with two forged signatures. The grade of similarity has been computed by introducing the term ‘Similarity Index’ (SI). Performance analysis reveals that after a careful tuning of vigilance parameter ( $\rho$ ), both serial and parallel processing are able to learn the exemplary patterns with 100% accuracy. While testing, it is noted that parallel processing performs better than the serial processing in terms of speed as well as identifying the forged signatures by computing the mismatch.

**Index Terms**—hand-written signature, automatic verification, ART-1, similarity index, forged signatures

## I. INTRODUCTION

Learning exemplary patterns is an important property of a Neural Network (NN). Based on the learning mechanisms, there are several types of NN, such as Adaptive Linear Net (ADALINE), multiple ADALINE (MADALINE), Perceptrons, Hopfield net and so forth (uses supervised learning methods), and Kohonen’s Self Organizing Map, Adaptive Resonance Theory (ART) net, which work by unsupervised methods [1]. This paper focuses on ART type-1.

Adaptive Resonance theory (ART) networks were first developed by Steven Grossberg and Gail Carpenter in 1987[2]. ART is of two types i.e. type-1 and type-2. ART-1 takes binary input vector, whereas, ART-2 takes analog/continuous input vector [3]. In this research, ART-1 network has been considered for automatic verification (offline) of hand-written signature. The reason for considering ART-1 in this study is that ART-1 learns

faster, consumes less memory space, and can adapt newer patterns without losing the initially stored patterns [3].

Signature of a person is the most widely used technique for identity verification. However, the issue is that, every new signature of a same person may vary due to re-initialization of scribbling in each time, which might be misused or forged by others. ART is able to store all the patterns including the variations, which might not be possible with other NN-based techniques, such as ADALINE/MADALINE or Perceptron. Hence, it invites a vast scope of research.

Due to increase in computation power, a lot of fast algorithms have been developed for hand written signature verification [4]. Here, we have implemented handwritten signature verification (offline) with ART using both (a) serial and (b) parallel programming techniques. In fact, for parallel programming we have used an API package commonly known as openMP (Open Multiprocessing) [4]. We compared the two algorithms with respect to time of execution and results. Available literature shows that using NNs and based on the parameters, such as (i) height, (ii) slant, (iii) pressure of pen tip and (iv) velocity of signing, signatures could be verified with 97% accuracy for the best case [5]-[7].

Hidden Markov Model (HMM) was used for signature-verification. It was performed by simple analysis of alphabet sequences within the signature. According to this model, a signature was considered as a sequence of vectors related to each point of signature in its trajectory. In HMM matching between model and signature was performed by using the probability of how the original signature was calculated. If the probability is high, then only the signature was accepted. The use of Back propagation NN was also proposed with success for off-line signature verification [5].

Contour technique was proposed by [8], where the contour of the signature was generated by dilating the signature by various levels generating a band like structure. This dilated signature template was then

compared with the test signature template. Here they used color bands for various dilation levels and an EX-OR were used for color bands to find variation in signature segments. This technique was fast and simpler to implement and gave an accuracy of 75%.

Statistical Approach using correlation was proposed by [9]. But it failed in case of skilled forgeries. As this method usually describes the characteristics of the signature related to the shape of signature.

Structural or Syntactic approach is an pattern recognition technique which represents patterns in the form of symbolic data structures viz. Trees, graph, strings etc. To verify a forge signature, its' symbolic data was compared with number of prototypes which are stored in the database. These structural features used modified direction and transition distance feature (MDF) [10] which extracts the transition locations. MDF are based on relational organization of low-level features into higher-level structures.

Wavelet-based approach was used by [11] where both static and pseudo dynamic features could be extracted from the original signature and processed by wavelet transform, which were then converted to sub-bands. This increased the difference between original and forged signatures. This method gave an average error rate of 12.57% for English signature and 13.96% for Chinese Signature.

Handwritten Signature verification (offline) is also done by using Adaptive Resonance Theory Method [12]. In this work, they have used ART-2 net for recognizing very similar looking but forged signature. In this study, the accuracy rate is almost 100%.

Associative Memory Net (AMN) approach was used for recognizing Handwritten Signature Verification [13], [14]. Here, the accuracy rate 92.3%.

Adaptive Resonance Theory (ART) method is also used for signature verification purpose. Based on 1-bit quantized pressure pattern in time domain, the work was being proposed. The timing information is used for screening for first stage screening of incoming signatures using ART-1 networks with various values of vigilance parameter [15].

Edge Detection can be another method for signature verification, where edge of the signature can be considered for training and testing [16].

## II. METHODOLOGY

The study has been performed in the following steps:

- Step-1:** Collecting hand written signatures
  - Step-2:** Extracting the features of all the signatures by to get all the gray-scale values
  - Step-3:** development of ART-1 net on 'C' language with (i) serial and (ii) parallel processing
  - Step-4:** Training ART net with the 'original' signature, and
  - Step-5:** Testing ART net with two forged signatures and compute the error by noting the % of mismatch.
- Step-1: Hand signature collection:**

Figures 1, 2a, and 2b show the hand-written signatures – both original and forged, collected for this work. The size of the signatures is 324x210 dpi.

In the next stage, Similarity Index (SI) has been computed between each of the forged signatures and the original signature using equation 1. The arrangements of pixels ('on' and 'off') in the forged signatures are compared with that of the original signature row and column-wise. The disparities/dissimilarities are then noted. In equation 1,  $D_p$  is the number of 'dissimilar pixels' and  $T_p$  is the total number of pixels. The SIs computed for forged signature 1 and 2 are ~51%.

$$SI = \frac{1 - D_p}{T_p} \cdot 100 \quad (1)$$

### Step-2: Feature extraction:

We extracted the pixel values in RGB (Red-Green-Blue) format and then converted it to gray scale format by using the following standard relation.

$$Gray\ value = 0.33 \times R + 0.56 \times G + 0.11 \times B \quad (2)$$

It is important to note that we have used a text file to extract the pixel value in the binary form using the following conditional statements.

If **gray value** > 0

Then append a '1' to the text file.

Else

Append a '0'.

A sample of pixel values are given in Appendix-A.

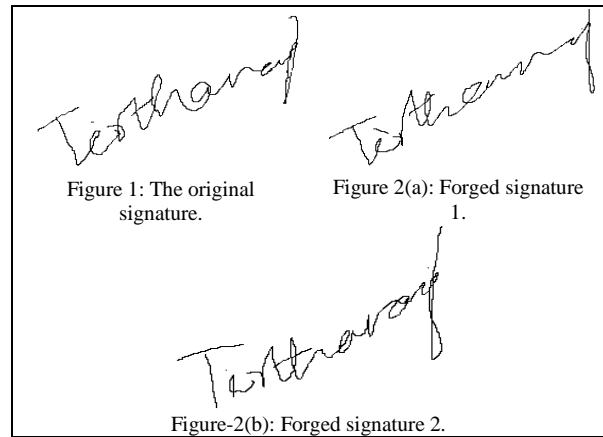


Figure 1: The original signature.

Figure 2(a): Forged signature 1.

Figure-2(b): Forged signature 2.

### Step-3 and 4: Development of ART-1 algorithm and its training:

As already mentioned, it has been developed on 'C' language. Figure 3 shows the schematic diagram of ART-1 structure. The implementation algorithm is as follows:

Step-0: Initialize the parameters:

$$\alpha > 1 \text{ and } 0 < \rho \leq 1$$

Initialize the weights:

$$0 < b_{ij}(0) < \alpha / (\alpha - 1 + n) \text{ and } t_{ji}(0) = 1$$

Step-1: Perform Steps 2-13 when stopping condition is false.

Step-2: Perform Steps 3-12 for each training input.

Step-3: Set activation of all  $F_2$  units to zero. Set the activation of  $F_1(a)$  units to input vectors.

Step-4: Calculate the norm of s:

$$\|s\| = \sum_i s_i \quad (3)$$

Step-5: Send input signal form  $F_1(a)$  layer to  $F_1(b)$  layer:

$$x_i = s_i \quad (4)$$

Step-6: For each F node that is not inhibited, the following rule should hold:

$$\text{If } y_j \neq -1, \text{ then } y_j = \sum_i b_{ij} x_i \quad (5)$$

Step-7: Perform Steps 8-11 when reset is true.

Step-8: Find J for  $y_j \geq y_j$  for all nodes j. If  $y_j = -1$ , then all the nodes are inhibited and note that this pattern cannot be clustered.

Step-9: Recalculate activation of X of  $F_1(b)$ :

$$x_i = s_i t_i \quad (6)$$

Step-10: Calculate the norm of vector x:

$$\|x\| = \sum_i x_i \quad (7)$$

Step-11: Test for the reset condition.

If  $\|x\|/\|s\| < \rho$ , then inhibit node J,  $y_j = -1$ . Go back to Step 7 again

Step 7 again

Else if  $\|x\|/\|s\| \geq \rho$ , then proceed to the next step (Step 12).

Step-12: Perform weight updation for node J (fast learning):

$$b_{ij}(\text{new}) = \alpha x_i / (\alpha - 1 + \|x\|) \quad (8)$$

$$t_{ji}(\text{new}) = x_i \quad (9)$$

Step-13: Test for the stopping condition. The stopping conditions may be:

- No change in weights.
- No reset of units.
- Maximum number of epoch reached.

The symbols used in this algorithm:

**n** = number of components in input training vector;

**m** = maximum number of cluster units that can be formed;

**$\rho$**  = vigilance parameter (set between 0 and 1);

**$\alpha$**  = learning trials;

**$b_{ij}$**  = bottom-up weights;

**$t_{ji}$**  = top-down weights (Weights from  $Y_j$  of  $F_2$  layer to  $X_i$  unit of  $F_1(b)$  layer);

**s** = binary input vector;

**x** = activation vector for  $F_1(b)$  layer;

**$\|x\|$**  = norm of vector x and is defined as the sum of components of  $x_i$  ( $i=1$  to  $n$ ).

It is important to mention that both the serial and parallel processing using *OpenMP* were executed in Linux environment.

**System specification:** It may be noted that, both ‘serial’ and ‘parallel’ processing has been executed in a PC with Intel dual core processor, 1 GB RAM, and 2 GHz.

**Step-5: Testing the performance of ART-1**

The forged signature is passed to the trained ART-1 network and the number of updated  $b_{ij}$  is counted. Now the  $b_{ij}$  updated during the training and the new  $b_{ij}$  after testing is compared.

The ratio of equal  $b_{ij}$  s to the total  $b_{ij}$  of training  $\times 100$  gives the percentage of matching of the two signatures from this result the tested signature can be accepted or rejected.

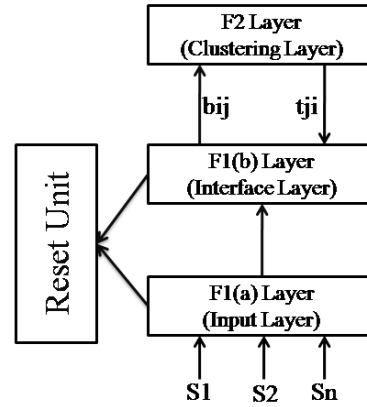


Figure-3: Structure of ART-1.

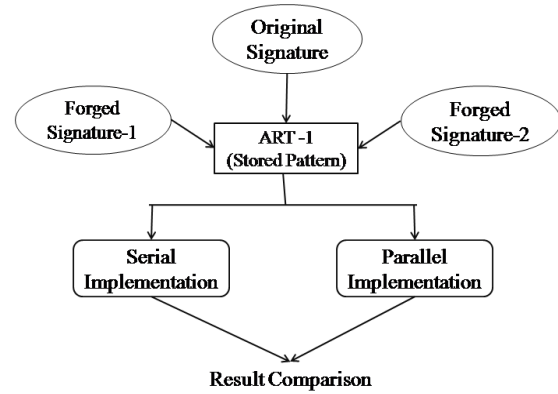


Figure-4: Training and testing of ART-1.

### III. RESULTS

The average similarity index (SI) between the original and forged signatures near 60%, which may have high chance of matching, instead of rejecting the forged signatures. It is desired that even with slightest difference, the network must be able to differentiate those from the original signature based on its learning and assigned vigilance. It is certainly a real-world challenge to curb this issue. The paper suggests that vigilance parameter ( $\rho$ ) needs to be optimally set, which is the first challenge. In this work, optimum  $\rho$  has been set based on the percentage of mismatch (which is the squared error) through a detail parametric study. Table-1 and 2 show the parametric study of setting  $\rho$ . The second challenge is to assure that the network learns the exemplary patterns through several observations. The third challenge is that the learning and its execution must be accomplished at minimum time. When original signature is checked with itself, it is noted that the net learns 100% exemplary patterns at average time of 13.70 sec in case of serial

processing (see table 1). In case of parallel processing, 100% exemplary pattern has been learnt with much less time, i.e., 6.20 sec (see table 2).

While detecting the forged signatures, it is noted that up to 50% mismatch could be detected by serial processing with average time of 18.85 sec with  $\rho=0.99$ . In case of parallel processing such amount of mismatch could be detected with average of 7.01 sec, which is much less, than the time consumed during serial processing. Also, during the parallel processing the values of  $\rho$  widely varies yielding more flexibility to the network. In this study, mismatches are identified with  $\rho$  values 0.1, 0.49, 0.68 and 0.99 respectively.

TABLE I. RESULTS OF SERIAL PROCESSING [A = 100]

$\rho$	Original vs. Original		Original vs. Forged1		Original vs. Forged2	
	Mismatch (%)	Time (s)	Mismatch (%)	Time (s)	Mismatch (%)	Time (s)
0.10	0.01	13.20	48.91	14.40	47.8	13.90
0.20	0.00147	14.00	48.975	13.20	49.171	13.90
0.30	0.001	13.80	49.21	13.90	49.170	13.80
0.49	0.01	13.70	49.21	13.90	49.17	13.60
0.68	0.0014	13.7	49.21	13.90	49.07	13.40
0.80	0.001	14.00	48.97	14.10	48.76	11.70
0.99	0.01	13.90	50.007	18.70	50.07	19.00

TABLE II. RESULTS OF PARALLEL PROCESSING [ $\alpha = 100$ ]

$\rho$	Original vs. Original		Original vs. Forged1		Original vs. Forged2	
	Mismatch (%)	Time (s)	Mismatch (%)	Time (s)	Mismatch (%)	Time (s)
0.10	0.01	8.22	48.01	6.07	50.9	4.37
0.20	0.02	6.059	48.07	5.95	49.171	5.051
0.30	0.001	6.20	50.01	4.71	49.172	5.93
0.49	0.02	6.9	50.9	8.20	50.7	7.8
0.68	0.02	6.98	50.09	8.25	50.70	7.80
0.80	0.80	0.01	7.09	48.97	8.99	49.00
0.99	0.01	6.40	50.007	6.89	50.07	8.09

Figure-5 is a plot drawn to compare the results of serial and parallel processing. It shows that, at  $\rho=0.3$  the parallel implementation gives better result by consuming only 5.61 sec during execution. Figure 6a and 6b shows the parametric study on different vigilance parameters ( $\rho$ ) vs. mismatch (i.e. the squared errors) in case of first forged signature for the serial and parallel processing, while figures 7a and 7b plots the same for the second forged signature. These are discussed below.

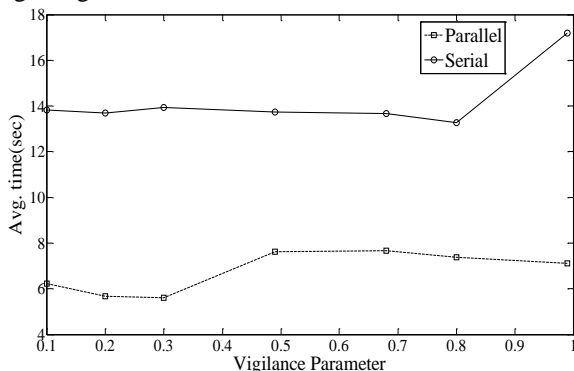


Figure-5. Plot showing the Average execution time vs. Vigilance parameter ( $\rho$ ) in 'Serial' and 'Parallel' processing.

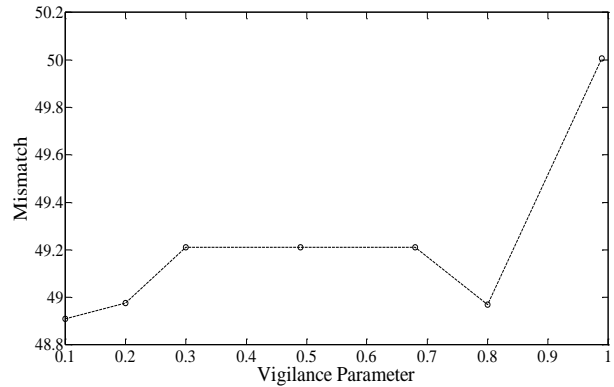


Figure-6a. Plot showing the 'Squared error' produced with several 'Vigilance parameter ( $\rho$ )' in 'Serial' processing for first forged signature.

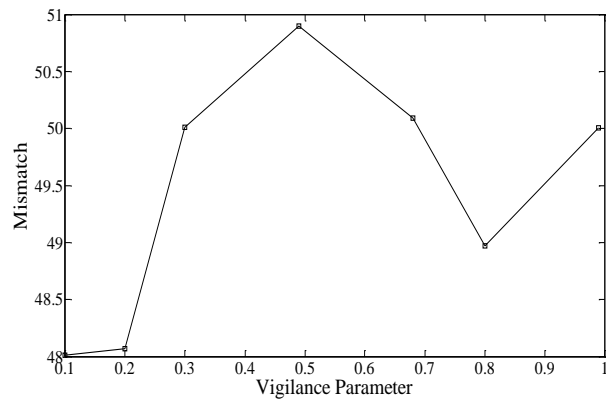


Figure-6b. Plot showing the 'Squared error' produced with several 'Vigilance parameter ( $\rho$ )' in 'Parallel' processing for first forged signature.

From figures 6a and 6b, it may be noted that for the first forged signature, in case of serial and parallel processing the maximum mismatches are found with  $\rho = 0.99$  and  $0.5$ , respectively. On the other hand, from figures 7a and 7b, it may be noted that for the second forged signature, in case of serial and parallel processing the maximum mismatches are found with  $\rho = 0.99$  and  $0.45$  &  $0.7$ , respectively. Therefore,  $\rho$  values between  $0.45 - 0.99$  might be able to catch the forged signatures mostly.

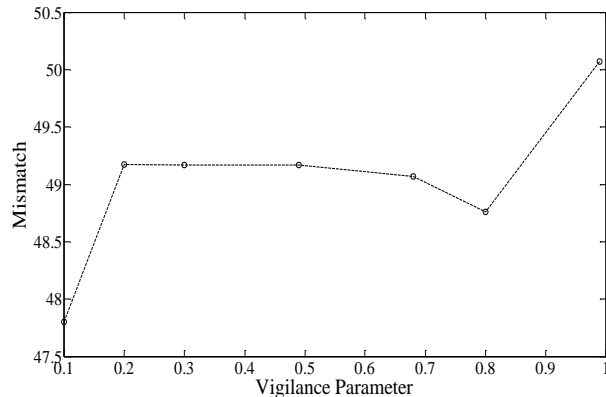


Figure-7a. Plot showing the 'Squared error' produced with several 'Vigilance parameter ( $\rho$ )' in 'Parallel' processing for second forged signature.



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